Machine learning and deep learning for demographic and selection inference

Flora Jay, CNRS, LISN
Matteo Fumagalli, QMUL
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+ credits for some slides: T Sanchez
About us

Flora Jay (CNRS) + Matteo Fumagalli (QMUL)

www.evogenomics.ai
sign up to the mailing list for seminars and training opportunities
(e.g., 20th June: Jonas Meisner)
ImaGene: a convolutional neural network to quantify natural selection from genomic data

Luis Torada, Lucrezia Lorenzon, Alice Beddis, Ulas Isildak, Linda Pattini, Sara Mathieson & Matteo Fumagalli

BMC Bioinformatics 20, Article number: 337 (2019) | Cite this article

SPECIAL ISSUE | Open Access | 

Distinguishing between recent balancing selection and incomplete sweep using deep neural networks

Ulas Isildak, Alessandro Stella, Matteo Fumagalli

First published: 22 March 2021 | https://doi.org/10.1111/1755-0998.13379

Detecting adaptive introgression in human evolution using convolutional neural networks

Graham Gower, Pablo Iñáez Picazo, Matteo Fumagalli, Fernando Racimo
University of Copenhagen, Denmark; Imperial College London, United Kingdom

Tools and Resources - May 23, 2021

Artificial intelligence can help spot traces of natural selection

by Hayley Dunning
22 March 2021
Admixture and assortative mating

Local ancestry

Continuous ancestry tract length
(100 ind, 22 windows, 3 ancestries, 2 chr aut/X)

Continuous ancestry tract length

Mean across individuals
Input:
(22 windows, 3 ancestries, 2 chr aut/X)

common dense branch

SB1
SB2
AM1
AM2
A1
Machine learning (ML) in evolutionary genomics

Morning session: introduction to
- basic concepts in supervised ML (Matteo)
- neural networks (Matteo)
- deep learning (Flora)
- unsupervised learning (Flora)
with examples from the literature.
Machine learning (ML) in evolutionary genomics

Afternoon and evening sessions:

- simple neural networks with keras and ImaGene (Matteo)
- advanced architectures with pytorch (Flora)
- scalable deep learning with dnaDNA (Flora)

with applications on detecting selection and inferring demographic histories.
Machine learning for population genetics

A (gentle and brief) introduction

Matteo Fumagalli
Intended Learning Outcomes

By the end of this very first part, you will be able to:

- Provide a basic definition of machine learning
- Illustrate the concepts of data, labels, and task
- Describe the difference between unsupervised and supervised learning
What is machine learning?

A typical example

**TASK:**
predict \( y \) from \( x \)

---

What is machine learning?

A typical example

**TASK:** predict $y$ from $x$

Data + Task: ? slide from Flora
What is the data?

- Learning something from data
  data = multidimensional object with e.g. lots of samples (rows) and lots of variables/predictors/factors/features/markers ...
  (one vector/one matrix/several matrix per sample)

| loc1 | loc2 | loc3 | ...
|------|------|------|------
| ind1 | A/A  | C/C  | C/G  |
| ind2 | T/A  | C/C  | G/G  |
|      |      |      |      |

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Quantitative and qualitative variables

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<tr>
<th>loc1</th>
<th>loc2</th>
<th>Sport activity</th>
<th>Hours of free time</th>
<th>Disease X?</th>
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<tr>
<td>ind1</td>
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multidimensional and heterogeneous data
What is the data?

- Learning something from **data**
  
  \[ \text{data} = \text{multidimensional object with e.g lots of samples (rows) and lots of variables/predictors/factors/features/markers ... (one vector/one matrix/several matrix per sample)} \]

Images with colors - micrographs of yeast cells expressing GFP-tagged proteins

Heterogeneous

MRI slices ~3D

temporal

slide from Flora
What is the learning **task**?

- Data with or without label

- What's a label? a target class or a target value observed for each sample. *Data are not always labeled. They can also have multiclass labels.*
  - *ex: pic of dog/person/car..., price of house, level of cholesterol*

- Task/objective?
What is the learning **task**?

- Data with or without label

- What's a label? a target class or a target value observed for each sample. *Data are not always labeled. They can also have multiclass labels* ex: *pic of dog/person/car..., price of house, level of cholesterol*

- Task/objective?

- Task/objective?

---

Task = predicting gene function labels

Task = predicting protein 3D structure/contact map from DNA sequences and secondary structure, ... (blue=truth, red=pred)

---

Task = identifying groups (clusters) of eg single-cell (T cells, NK cells, ...) with similar pattern of gene expression

Tang et al, JEM 2017
Unsupervised vs. Supervised Tasks

- Learning something from **data**
- Either **unsupervised** (no labels) or **supervised** (discrete or continuous labels)

Can you think of examples of unsupervised and supervised tasks in evolutionary genomics?
...

Supervised learning

- **Supervised** = Learn a relationship (a general model) linking input data (or features) to observed labels

Classification (predict a class)  
Regression (predict a variable)

What for:
- Predict labels of new unlabeled samples (eg what's on an image?),
- Understand better the relationship between features and the label (eg understand which set of genes allow to predict a disease risk),
- ...

(Flora will cover unsupervised learning later today)

slide from Flora
Intended Learning Outcomes

At the end of this very first part, you are now able to:

- Provide a basic definition of machine learning
- Illustrate the concepts of data, labels, and task
- Describe the difference between unsupervised and supervised learning
Intended Learning Outcomes

By the end of this session, you will be able to:

- Describe the three key components of a classifier: score function, loss function, optimisation
- Identify the elements of a neural networks, including neurons and hyper-parameters
- Illustrate the layers in a neural network
- Demonstrate how to implement, train and evaluate neural networks in python
What do you see?
What does the computer see?

Is it THAT difficult?
Challenges

- invariant to the cross product of all these variations
- retaining sensitivity to the inter-class variations
Data-driven approach

We need a (large) training dataset of labeled images.
Pipeline for image classification

1. Training set: \(N\) images of \(K\) classes

2. Learning: training a classifier

3. Evaluation: against the ground truth
Nearest Neighbour Classifier

Figure 1: CIFAR-10 dataset: 60k tiny images of 10 classes.

The nearest neighbour classifier will take a test image, compare it to every single one of the training images, and predict the label of the closest training image.
Nearest Neighbour Classifier

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<th>56</th>
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Nearest Neighbour Classifier

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<tr>
<td>56 32 10 18</td>
<td>10 20 24 17</td>
</tr>
<tr>
<td>90 23 128 133</td>
<td>8 10 89 100</td>
</tr>
<tr>
<td>24 26 178 200</td>
<td>12 16 178 170</td>
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<tr>
<td>2 0 255 220</td>
<td>4 32 233 112</td>
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Nearest Neighbour Classifier

<table>
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<th>test image</th>
<th>training image</th>
<th>pixel-wise absolute value differences</th>
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<td>56 32 10 18</td>
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<td>2 0 255 220</td>
<td>4 32 233 112</td>
<td>2 32 22 108</td>
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456
The choice of distance

L1 distance: \( d_1(I_1, I_2) = \sum_{\text{pixel}} |I_{1p} - I_{2p}| \)

L2 distance: \( d_1(I_1, I_2) = \sqrt{\sum_{\text{pixel}} (I_{1p} - I_{2p})^2} \)

What's their accuracy?
What's human accuracy?
What's state-of-the-art neural networks’ accuracy?

Let's give it a try!
IUCN Red List of Threatened Species

LC: least concern

VU: vulnerable

EN: endangered

CR: critically endangered
The challenge: predict whether a species is endangered, vulnerable or of least concern from genomic data.

Let’s try it!
Nearest Neighbour Classifier

What went wrong when using this algorithm to predict the label "conservation status" from population "genotype" data? Any undesired behaviours? Any suggestions on how we can improve our prediction accuracy?

Mentimeter live survey:
Figure 2: An example of the difference between Nearest Neighbor and a 5-Nearest Neighbor classifier, using 2-dimensional points and 3 classes (red, blue, green).

What value of $k$ should we use? Which distance?
Hyperparameter tuning

The engineer says: "We should try out many different values and see what works best."

Agree or disagree?
Validation test

The good engineer says: "Evaluate on the test set only a single time, at the very end."

- Split your training set into training set and a validation set.
- Use validation set to tune all hyperparameters.
- At the end run a single time on the test set and report performance.
Data splits

**Figure 3:** The training set is split into folds: 1-4 become the training set while 5 is the validation set used to tune the hyperparameters.

Where is the Nearest Neighbour classifier spending most of its (computational) time?
Wrap up

- the problem of image classification: predicting labels for novel test entries
- training set vs testing set
- a simple Nearest Neighbour classifier requires hyperparameters
- validation set to tune hyperparameters
- Nearest Neighbour classifier has low accuracy (distances based on raw pixel values!) and is expensive at testing

Our aim: a solution which gives very high accuracy, discards the training set once learning is complete, and evaluates a test image in less than a millisecond!
Linear classification

New approach based on:

- **score function** to map raw data to class scores
- **loss function** to quantify the agreement between predicted and true labels
Parameterised mapping from images to label scores

Our aim is to define the score function that maps the pixel values of an image to confidence scores for each class.

Assuming that:

N images, each with dimensionality D, and K distinct classes

\( x_i \in \mathbb{R}^D \) is image \( i \)-th with dimensions \( D \) and label \( y_i \), with

\( i = 1 \ldots N \) and \( y_i \in 1 \ldots K \)

then we define a **score function**: \( f : \mathbb{R}^D \rightarrow \mathbb{R}^K \)
Linear classifier

Linear mapping: $f(x_i; W, b) = Wx_i + b$

$W$ are called **weights** and $b$ is the **bias** vector.

What are the dimensions of $x_i$, $W$ and $b$?
Linear classifier

Linear mapping: \( f(x_i; W, b) = Wx_i + b \)

\( W \) are called **weights** and \( b \) is the **bias** vector.

What are the dimensions of \( x_i, W \) and \( b \)?

- \( x_i \) has size \([D \times 1]\)
- \( W \) has size \([K \times D]\)
- \( b \) has size \([K \times 1]\)
Linear classifier

input image

stretch pixels into single column

\[
\begin{array}{cccc}
0.2 & -0.5 & 0.1 & 2.0 \\
1.5 & 1.3 & 2.1 & 0.0 \\
0 & 0.25 & 0.2 & -0.3 \\
\end{array}
\]

\[
\begin{array}{c}
56 \\
231 \\
24 \\
2 \\
\end{array}
\]

\[
\begin{array}{c}
1.1 \\
3.2 \\
-1.2 \\
\end{array}
\]

\[
\begin{array}{c}
-96.8 \\
437.9 \\
61.95 \\
\end{array}
\]

\[f(x_i; W, b)\]

cat score
dog score
ship score
Interpreting a linear classifier (i)

\[
\begin{array}{cccc}
0.2 & -0.5 & 0.1 & 2.0 \\
1.5 & 1.3 & 2.1 & 0.0 \\
0 & 0.25 & 0.2 & -0.3 \\
\end{array}
\]
Interpreting a linear classifier (ii)
Interpreting a linear classifier (iii)

Template (or prototype) matching.
**Bias trick**

**Our new score function:**

\[ f(x_i; W) = Wx_i \]

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**new, single W**
Loss function*

To measure our "unhappiness" with predicted outcomes.

* sometimes called cost function or objective
Multiclass Support Vector Machine (SVM) loss

The SVM loss is set so that the SVM "wants" the correct class for each image to have a higher score than the incorrect ones by some fixed margin.

\[ L_i = \sum_{j \neq y_i} \max(0, s_j - s_{y_i} + \delta) \]

Example:
\( s = [13, -7, 11], y_i = 0, \delta = 10 \)
\( L_i = \)
The SVM loss is set so that the SVM "wants" the correct class for each image to have a higher score than the incorrect ones by some fixed margin.

\[
L_i = \sum_{j \neq y_i} \max(0, s_j - s_{y_i} + \delta)
\]

Example:
\[
s = [13, -7, 11], y_i = 0, \delta = 10
\]
\[
L_i = 8
\]
Hinge loss

$max(0, -)$ or $max(0, -)^2$
Regularisation

If \( W \) correctly classifies each sample, then all \( \lambda W \) with \( \lambda > 1 \) will have zero loss.

Which \( W \) should we choose?
Regularisation

If \( W \) correctly classifies each sample, then all \( \lambda W \) with \( \lambda > 1 \) will have zero loss.

Which \( W \) should we choose?

Our new multiclass SVM loss function is:

\[
L = \frac{1}{N} \sum_i \sum_{j \neq y_i} \left[ \max(0, f(x_i; W) \cdot_j - f(x_i; W) \cdot_{y_i} + \delta) \right] + \lambda \sum_k \sum_l W_{k,l}^2
\]

including one data loss and one regularisation loss term \( \lambda R(W) \), specifically L2 penalty.
Softmax classifier

Generalisation of the binary logistic regression classifier to multiple classes.

Cross-entropy loss function:

\[ L_i = - \log \left( \frac{e^{f_{y_i}}}{\sum_j e^{f_j}} \right) \]  (1)
SVM vs. Softmax classifier

Matrix multiply + bias offset

\[ W = \begin{bmatrix} 0.01 & -0.05 & 0.1 & 0.05 \\ 0.7 & 0.2 & 0.05 & 0.16 \\ 0.0 & -0.45 & -0.2 & 0.03 \end{bmatrix}, \quad b = \begin{bmatrix} -15 \\ 22 \\ 56 \end{bmatrix} \]

\[ x_i = \begin{bmatrix} \vdots \\ y_i = \begin{bmatrix} 2 \end{bmatrix} \end{bmatrix} \]

Hinge loss (SVM)

\[
\max(0, -2.85 - 0.28 + 1) + \\
\max(0, 0.86 - 0.28 + 1) = 1.58
\]

Cross-entropy loss (Softmax)

\[
\exp(-2.85) \\
\exp(0.86) \rightarrow \frac{0.058}{0.86 + 2.36} = 0.016 \\
\exp(0.28) \rightarrow \frac{1.32}{1.32 + 2.36} = 0.353
\]

\[-\log(0.353) = 1.04\]
Wrap up

- A score function maps image pixels to class scores (using a linear function that depends on $W$ and $b$).
- Once we learning is done, we can discard the training data and prediction is fast.
- A loss function (e.g. SVM and Softmax) measures how compatible a given set of parameters is with respect to the ground truth labels in the training dataset.
Examples of using SVM to detect natural selection

Searching for Footprints of Positive Selection in Whole-Genome SNP Data From Nonequilibrium Populations

Pavlos Pavlidis,*−1 Jeffrey D. Jensen† and Wolfgang Stephan*

*Department of Biology II, Ludwig-Maximilians-University Munich, 82152 Planegg, Germany and †Program in Bioinformatics and Integrative Biology, University of Massachusetts Medical School, Worcester, Massachusetts

Manuscript received March 9, 2010
Accepted for publication April 7, 2010
Examples of using SVM to detect natural selection

Learning Natural Selection from the Site Frequency Spectrum

Roy Ronen,* Nitin Udpa,* Eran Halperin,† and Vineet Bafna‡

*Bioinformatics and Systems Biology Program, University of California, San Diego, California 92093, †The Blavatnik School of Computer Science and Department of Molecular Microbiology and Biotechnology, Tel-Aviv University, Tel-Aviv 69978, Israel; ‡International Computer Science Institute, Berkeley, California 94704, and ‡Department of Computer Science and Engineering, University of California, San Diego, California 92093
Supervised Machine Learning for Population Genetics: A New Paradigm

Daniel R. Schrider¹,* and Andrew D. Kern¹,*
Key components for classification tasks

1. score function
2. loss function
3. optimisation

Optimisation is the process of finding the set of parameters $W$ that minimise the loss function $L$. 
Visualising the loss function

If $W_0$ random starting point, $W_1$ random direction, then compute $L(W_0 + aW_1)$ for different values of $a$.

(averaged across all images, $x_i$)
Optimisation

- Random search
- Random local search
- Gradient descent (numerical or analytical)
Hyperparameters

**Step size** or learning rate

**Batch size:**
Compute the gradient over batches (e.g. 32, 64, 128...) of the training data.
Wrap up

The 3 elements: score function, loss function, optimisation. Next: let’s put them all together in a neural network.
Neurons

\[
\sum_i w_i x_i + b \rightarrow f \left( \sum_i w_i x_i + b \right)
\]
Activation functions

It defines the *firing rate*

![Sigmoid function graph](image1)

Sigmoid non-linearity squashes real numbers to range between [0, 1]

![Rectified Linear Unit (ReLU) graph](image2)

Rectified Linear Unit (ReLU):

\[ f(x) = \max(0, x) \]
Neural network architecture

Collection of neurons connected in an acyclic graph. Last output layer represents class scores.

A 2-layer Neural Network

Size:
Neural network architecture

Collection of neurons connected in an acyclic graph. Last output layer represents class scores.

A 2-layer Neural Network
Size: 4 + 2 = 6 neurons, [3 x 4] + [4 x 2] = 20 weights and 4 + 2 = 6 biases, for a total of 26 learnable parameters.

A 3-layer Neural Network
Size:
Neural network architecture

Collection of neurons connected in an acyclic graph. Last output layer represents class scores.

A 2-layer Neural Network
Size: $4 + 2 = 6$ neurons, $[3 \times 4] + [4 \times 2] = 20$ weights and $4 + 2 = 6$ biases, for a total of 26 learnable parameters.

A 3-layer Neural Network
Size: $4 + 4 + 1 = 9$ neurons, $[3 \times 4] + [4 \times 4] + [4 \times 1] = 12 + 16 + 4 = 32$ weights and $4 + 4 + 1 = 9$ biases, for a total of 41 learnable parameters.
Representational power

Given any continuous function \( f(x) \) and some \( \epsilon > 0 \), there exists a Neural Network \( g(x; W) \) with one hidden layer (with a reasonable choice of non-linearity, e.g. sigmoid) such that for all \( x \),

\[
| f(x) - g(x) | < \epsilon.
\]

In other words, the neural network can approximate any continuous function.

In practice, more layers work better...
Setting up the architecture

Capacity vs. ?
Setting up the architecture

Capacity vs. ? Overfitting
We aim at a better generalisation.
Setting up the data

Data preprocessing:
- mean subtraction
- normalisation
- PCA and Whitening
Setting up the model

Weight initialisation:
- all zero
- small random numbers
- calibrate the variances
- sparse
Setting up the model

Regularization

Options: L2, L1, maxnorm and dropout.
Dropout can be interpreted as sampling a Neural Network within the full Neural Network, and only updating the parameters of the sampled network based on the input data.
Setting up the model

Loss functions:
- SVM (hinge loss)
- cross-entropy
- hierarchical softmax
- attribute classification
- regression (?)
Setting up the learning effects of different learning rates

loss decay
Setting up the learning

Training vs. validation accuracy

- **Training accuracy**
- **Validation accuracy:** little overfitting
- **Validation accuracy:** strong overfitting

Graph showing the comparison between training and validation accuracy over epochs.
Wrap up

- Neural Networks are made of layers of neurons/units with activation functions
- Choice of the architecture: capacity vs overfitting
- Preprocessing of the data and choice of hyperparameters for the model and learning
ANNs to detect natural selection
ANNs to detect natural selection

Deciphering signatures of natural selection via deep learning

Xinghu Qin\textsuperscript{1*}, Charleston W. K. Chiang\textsuperscript{2}, Oscar E. Gaggiotti\textsuperscript{1*}

\textsuperscript{1} Centre for Biological Diversity, Sir Harold Mitchell Building, University of St Andrews,
Fife, KY16 9TF, UK
What about images or highly-dimensional data (like images)? Can we use neural networks straight from individual data points? What’s the issue?
Intended Learning Outcomes

At the end of this session, you are now able to:

- Describe the three key components of a classifier: score function, loss function, optimisation
- Identify the elements of a neural network, including neurons and hyper-parameters
- Illustrate the layers in a neural network
- Demonstrate how to implement, train and evaluate neural networks in python
Practical
The case of LCT gene and lactase persistence (https://en.wikipedia.org/wiki/Lactase_persistence)

Task: to predict positive selection at LCT locus in European populations using deep learning in python.
Machine learning and deep learning for demographic and selection inference

Flora Jay, CNRS, LISN
Matteo Fumagalli, QMUL
Jean Cury, Erik Madison Bray, LISN

+ credits for some slides: T Sanchez
About us

Flora Jay (CNRS) + Matteo Fumagalli (QMUL)

EvoGenomics.AI

www.evogenomics.ai
sign up to the mailing list for seminars and training opportunities
(e.g., 20th June: Jonas Meisner)
Outline

Machine Learning: basic concepts and terminology
ML, application to popgen ; neural networks

I. From ABC to deep learning for population genetics
II. Learning directly from SNP data with neural networks
III. Dissecting two published networks for effective population size inference
IV. Opening on applications of unsupervised deep learning to popgen
V. Tonight’s hands-on: building/training/re-using DNNs for population genetics (demography/selection) inference with dnadna
Approximate Bayesian Computation:
likelihood free inference based on simulations

- Data summarized by **handcrafted summary statistics**
- **Real and simulated** summary statistics are **compared**
- The comparison informed on the likely demographic scenario
- Application to demography: Boitard et al 2016, Jay et al 2019 and many other works

Here and in all DL methods presented afterwards training is based on large datasets of **simulated data with labels** (i.e. for which we know the evolutionary parameters)
Deep learning on summary statistics (+ABC)

- Generally, fully connected net / multilayer perceptron (MLP), e.g.:
  - Selection and demo inference, Sheehan and Song 2016 (no ABC)
  - Model selection+inference (archaic admixture models), Mondal et al. 2019 (with ABC)

- Those were inspired by Jiang et al 2017 (MLP)
  
  But see as well Creel 2017 (MLP), Raynal et al. 2017 (random forest), Fernhead and Prangle 2012 (posterior mean as s(.)

---

**Diagram:**

- Genetic dataset \(D\)
  - \(\text{SUMMARY}\)
    - Linkage Disequilibrium
    - Site Frequency Spectrum
    - Identity By State
    - Distribution Between Segregating Sites
    - \(\text{ad-hoc/expert/handcrafted sumstats}\)
  - Semi automatic sumstats (posterior mean)

- DNN
  - param 1
  - param 2
  - param \(p\)

- ABC
Deep learning on summary statistics

- Generally fully connected net / multilayer perceptron (MLP), e.g.:
  - Selection and demo inference, Sheehan and Song 2016 (no ABC)
  - Model selection+inference (archaic admixture models), Mondal et al. 2019 (with ABC)

Mondal et al. 2019: ABC [ MLP (joint SFS) ]

2 models selected among 8 models + parameter estimation

-> third archaic introgression in Asia and Oceania from Neandertal-Denisova clade or from Denisova related lineage (early divergence)
Reminder: you could bypass summary statistics

From summary statistics (handcrafted features):

\[Ex1\]
\[x_1 = \text{Height}\]
\[x_2 = \text{Nb legs}\]
\[x_n = \text{Hair}\]

\[\begin{align*}
\text{Prob(image is a cat)} \\
\text{Prob(image is a bird)}
\end{align*}\]
Reminder: you could bypass summary statistics

Internal layer(s): learn an hidden representation from the data (ie learn how to encode the data)

NOT handcrafted features!
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Deep learning on "raw" genetic data

- Process directly the genetic data to bypass handcrafted features
- Often convolution neural networks (CNN)
- Inspired by Jiang et al 2017 but previous works in popgen skip the ABC step

(e.g. DNN tries to predict N1, ... Np etc) and these are used later as automatic summary statistics (or automatic features) processed by ABC
Deep Learning (DL) = deep neural networks = nnet with multiple layers
Able to learn a hierarchy of representations with increasing level of abstraction

Eg. for image:
pixel → edge → motif → part → full object → combination (eg landscape, scene)

Eg. for text:
letter → word → word group → sentence → story

A layer = trainable function that transforms input into features at a certain hierarchy level
Deep learning on "raw" genetic data

- Convolution networks work well for **computer vision**:

[Diagram of convolution networks]

*Lecun et al.*
1998

- Already used on **DNA sequences**:

[Diagram of DNA sequence analysis]

*Alipanahi et al.*
2015
Why using convolution networks? (convnet)

- **Fully connected:**
  - huge number of parameters to learn (each edge correspond to a weight)

- **Convnet**
  - locally connected
  - smaller number of parameters to learn

© Yann LeCun
DL - convolution

- Why using convolution networks? (convnet)

Convnet
locally connected
→ smaller number of
parameters to learn

© Yann LeCun
Convolution operation

• Convolution with padding and stride=1 → no dimension reduction

![Convolution example]

• No padding and/or stride > 1 → dimension reduction

![Convolution example]
Exercise

- Computer by hand a convolution operation (see below)
- Compute the number of parameters (how does it scale with input size)
- Design a 3x3 filter (with fixed weights) that could detect horizontal edges (detect a pattern ~ maximal activation for this pattern)

<table>
<thead>
<tr>
<th>Input data</th>
<th>Convolutional operation (with fixed weights)</th>
<th>Output ?</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 1 1 0 0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1 1 0 1 0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1 0 0 0 1</td>
<td>0.5 -1 2</td>
<td></td>
</tr>
<tr>
<td></td>
<td>-1 0.5 3</td>
<td></td>
</tr>
</tbody>
</table>
Exercise

- Computer by hand a convolution operation (see below)
- Compute the number of parameters
- Design a 3x3 filter (with fixed weights) that could detect horizontal edges (detect a pattern ~ maximal activation for this pattern)

![Convolutional operation (with fixed weights)]

Input data

\[
\begin{array}{ccc}
0 & 1 & 1 \\
0 & 1 & 0 \\
1 & 0 & 0 \\
\end{array}
\]

Convolutional operation (with fixed weights)

\[
\begin{array}{ccc}
0.5 & -1 & 2 \\
-1 & 0.5 & 3 \\
\end{array}
\]

Output?

\[
1.5\quad\ldots\quad\ldots
\]

\[
0 \cdot 0.5 + 1 \cdot (-1) + 1 \cdot 2 + 0 \cdot (-1) + 1 \cdot 0.5 + 0 \cdot 3
\]
Exercise

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Exercise

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<table>
<thead>
<tr>
<th>Input data</th>
<th>Convolutional operation (with fixed weights)</th>
<th>Output</th>
<th>Output of max pool operation</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 1 1 0 0</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0 1 0 1 0</td>
<td></td>
<td>-2 2.5</td>
<td>2.5</td>
</tr>
<tr>
<td>1 0 0 0 1</td>
<td></td>
<td>1.5 2.5 1</td>
<td></td>
</tr>
</tbody>
</table>

```
0 1 1 0 0
0 1 0 1 0
1 0 0 0 1
```

```
0.5 -1 2
-1 0.5 3
```
Exercise

- Computer by hand a convolution operation (see below)
- Compute the number of parameters
- Design a 3x3 filter (with fixed weights) that could detect horizontal edges (detect a pattern ~ maximal activation for this pattern)

<table>
<thead>
<tr>
<th>Input data</th>
<th>Convolutional operation (with fixed weights)</th>
<th>Output</th>
<th>OR applying a RELU activation and another conv filter (e.g. 2x2)</th>
<th>Output</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 1 1 0 0</td>
<td>0.5 -1 2</td>
<td>1.5 2.5 1</td>
<td>1.5 2.5 1</td>
<td>[...]</td>
</tr>
<tr>
<td>0 1 0 1 0</td>
<td>-1 0.5 3</td>
<td>-2 2.5 2</td>
<td>0 2.5 2</td>
<td>[...]</td>
</tr>
<tr>
<td>1 0 0 0 1</td>
<td></td>
<td></td>
<td>another conv filter with fixed weights</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>4 -0.1</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>-1.2 0.6</td>
<td></td>
</tr>
</tbody>
</table>
Exercise

- Computer by hand a convolution operation (see below)
- Compute the number of parameters
- Design a 3x3 filter (with fixed weights) that could detect horizontal edges (detect a pattern ~ maximal activation for this pattern)

Convolutional operation (with fixed weights) detecting horizontal edges

```
-1 -1 -1
1  1  1
-1 -1 -1
```
Reminder of steps for a simulation-based supervised ML approaches

- Define clearly your task
  - Regression/classification of xXx ; score function, loss
  - Define one or several models e.g. Constant size, Fluctuating size, Fluctuating+selection
  - Pick priors for the parameters of these models e.g. Ne~U[0,100], selection coeff~N(0,10), ...

- Randomly draw parameters

- Simulate thousands/millions of such SNP matrices thanks to genetic simulators (msprime, msms, slim, bactSLiMulator, ...) using the random parameters

- **Design**, train and evaluate a model directly on these matrices

Typical input for population genetics methods
DNN on "raw" data in popgen: SNPs (and distance) matrix

- Detection of recombination hotspot, *exchangeable CNN net*

- Inference of introgression, selection, recombination rate and population size histories with 5 parameters (3-step history), *CNNs*

---

Flagel et al. 2019

Chan et al. 2018
DNN on "raw" data in popgen: SNPs (and distance) matrix

- Predicting selection (under fixed demography), CNN

Torada et al.
2019
related: Isildak et al bioRxiv (balancing selection vs incomplete sweep),

- Inference of recombination with recurrent networks (RNN)

Adrion et al.
2020
DNN on "raw" data in popgen: SNPs (and distance) matrix

- Predicting fluctuating population size (21 steps), exchangeable CNN
Comparison and combination with ABC

Sanchez et al. 2020
DNN on "raw" data in popgen: SNPs (and distance) matrix

“Coalescent-based species delimitation meets deep learning: Insights from a highly fragmented cactus system.” Perez et al 2021

To keep going: the introduction of Sanchez*, Bray*, et al (preprint) lists many more papers on DNN for popgen

Sanchez*, Bray*, et al (preprint)  https://hal.archives-ouvertes.fr/hal-03352910v2
“Dnadna: Deep Neural Architecture for DNA - A deep learning framework for population genetic inference”
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Exercice: define the task and loss for a net that could inform you whether there was a strong decline of effective population size

What’s my model(s)? What are the parameters? Regression or classification task? --> loss?
Exercice: define the task and loss for a net that could inform you whether there was a strong decline of effective population size

What’s my model(s)? What are the parameters? Regression or classification task? -> loss?

*Inferred demographic model parameters $\hat{\delta}$*

Decline? OR Expansion?
Dissecting a NN architecture

- *Flagel et al. 2019* network
How?
Convolution operation

- Convolution with padding and stride=1 → no dimension reduction

- No padding and/or stride > 1 → dimension reduction
Pooling operation

- Pooling (max, average, sum pooling)
  -> reducing dimension without additional parameter to learn

https://medium.com/@RaghavPrabhu
Why a 2D convolution?

Flagel et al. 2019
Why a 2D convolution?

Flagel et al. 2019

But popgen data is different from a classical image!
How to be invariant?

- Solution 1: specify an **order**
ex: individual similarity (rows)SNP similarity (columns)

Flagel et al. 2018

Torada et al. 2019
How to be invariant?

- Solution 1: specify an order (ex: individual similarity) (e.g. Flagel et al. 2018, Torada et al. 2019, ...)

- Solution 2: data augmentation: apply transformation(s) to the input data that should not affect its label. Ex. in some tasks of computer vision: rotating images

Exercice: give examples of data augmentation relevant for population genomics
How to be invariant?

- Solution 1: specify an order (ex: individual similarity) (e.g. Flagel et al. 2018, Torada et al. 2019, ... )

- Solution 2: data augmentation (e.g. shuffling the lines)

- Solution 3: encode invariance in the network (permutation-invariant network, exchangeable network) (e.g. Chan et al. 2018, Wiqvist et al. 2019, Sanchez et al 2020)
Adapt the network to the data features

- **Invariant** to the permutation of rows

**Equivariant function**

\[ \phi(x_i) \]

**Invariant function**

\[ \rho(x) \]

---

Exercice: give an example of invariant operation
Adapt the network to the data features

- **Invariant** to the permutation of rows

**Equivariant function**

\[ \phi(x_i) \]

**Invariant function**

\[ \rho(x) \]

---

**Stacking** invariant and equivariant layers **covers the full space of permutation invariant** function (Zaheer et al. 2017, Lucas et al. 2018)

\[ \phi^1(x_i) \rightarrow \phi^2(x_i) \rightarrow \ldots \rightarrow \rho(x) \]
Adapt the network to the data features

- Each block of SPIDNA defines an equivariant function

Sanchez et al 2020
Our Neural Network Architecture: SPIDNA

Sequence Position Informed Deep Neural Architecture

- Combines relatives positions and SNPs
- Invariant to haplotype permutation
- Adaptive to the number of SNPs
Final note on DL applied to population genetics

• Still a **recent** “combo” (2016 for DL on summary statistics, 2018 for DL on raw population genetic data) -> space for creativity and new proposals!

• Remember some important rules in stat/ML/DL:
  
  • **Think** properly about your **task**, statistical **model**, **evaluation** scheme/metrics
  
  • **Watch out for overfitting**, use train/validation sets
  
  • **Compare** to previously published methods
    
    - Choose or explore **hyperparameter space** for each approach (grid search, Bayesian hyperoptimisation, ...) based on validation set
    
    - Final comparison on an **independent test set**

• Evaluate method **robustness** to data **corruption**, model **misspecification**, ...
  
  Particularly relevant for simulation-based inference approaches where simulators and simulation scenarios have underlying **assumptions** that can be violated in the real life.

• You might gain in accuracy but lose in **explainability**/interpretability (ex: CNN versus a previous approach based on SFS). Improving interpretability is actively studied in DL field.
Robustness?

- Eg to selection while predicting demography or vice versa

- To data damage, ...

Same care should be taken for all model-based inference models (even without simulations, such as PSMC, dadi etc.)

+ Additional unknown regarding what the NN is using
Interpretation?

Examples
- Sheehan and Song 2016. Pinpoint summary statistics used by the NN for a prediction
- Gower et al. 2021 Pinpoint parts of an image used for predicting adaptive introgression

Dream goal? And what about demography?

Can we have such a clear signal?
Active area of research in the machine/deep learning community
Deep learning hyper-parameters (HP)

- You still have to make decisions about (1) your architecture (#layers, #nodes per layer, layer type,...) ; (2) the algorithm/optimization hyper-parameters

- Usually done by training numerous networks with numerous HP and keeping the one performing the best. Can be done in a smart way with e.g. bayesian HP optimization. Automatic Deep Learning: active area of research

Just a taste of some NN algo hyper-parameters

<table>
<thead>
<tr>
<th>Name</th>
<th>Range</th>
<th>Default value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Learning rate</td>
<td>0.1, 0.01, 0.001, 0.0001</td>
<td>0.01</td>
</tr>
<tr>
<td>Batch size</td>
<td>64, 128, 256</td>
<td>128</td>
</tr>
<tr>
<td>Momentum rate</td>
<td>0.8, 0.9, 0.95</td>
<td>0.9</td>
</tr>
<tr>
<td>Weight initialization</td>
<td>Normal, Uniform, Glorot uniform</td>
<td>Glorot uniform</td>
</tr>
<tr>
<td>Per-parameter adaptive learning rate methods</td>
<td>RMSprop, Adagrad, Adadelta, Adam</td>
<td>Adam</td>
</tr>
<tr>
<td>Batch normalization</td>
<td>Yes, no</td>
<td>Yes</td>
</tr>
<tr>
<td>Learning rate decay</td>
<td>None, linear, exponential</td>
<td>Linear (rate 0.5)</td>
</tr>
<tr>
<td>Activation function</td>
<td>Sigmoid, Tanh, ReLU, Softmax</td>
<td>ReLU</td>
</tr>
<tr>
<td>Dropout rate</td>
<td>0.1, 0.25, 0.5, 0.75</td>
<td>0.5</td>
</tr>
<tr>
<td>L1, L2 regularization</td>
<td>0, 0.01, 0.001</td>
<td></td>
</tr>
</tbody>
</table>
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Unsupervised / Supervised Tasks

- Learning something from **data**
- Either **unsupervised** (no labels) or **supervised** (discrete or continuous labels)
Unsupervised learning

- **Learning something from data without labels**
- **Unsupervised = discovering patterns in data without prior knowledge**
  You do NOT have labels, or you do NOT use them

**Exercice:** Give examples of unsupervised tasks in population genetics

- 
- 
-
Unsupervised learning

- **Unsupervised = discovering patterns in data without prior knowledge**
  You do NOT have labels, or you do NOT use them

  - Dimension reduction methods, e.g. PCA, Matrix factorization
  - Clustering algorithms, e.g. K-means, hierarchical clustering, ...
  - Outlier detection (can be then used for filtering, ..)
  - ...

Unsupervised learning examples (not only deep neural nets here)

- Dimension reduction methods, e.g. PCA, Matrix factorization
- Clustering algorithms, e.g. K-means, hierarchical clustering, SNMF ...
- Outlier detection (can be then used for filtering, ..)

PCA to reduce high dimensional genotype data for human populations

*The 1st axis (ie the linear combination of markers) explains the largest part of the variance among samples. The 2nd axis explains the largest part of the remaining variance, and so on.*

Novembre et al 2008
Neural networks for unsupervised tasks

(i) reconstructing oneself after a strong reduction in dimension

Convolutional Autoencoder (AE)
Ausmees et al 2021

Variational Autoencoder (VAE)
Battey et al 2021
Non-linear dimension reduction based on neural networks for visualizing genetic data

Yelmen et al. 2021
restricted Boltzman machine
RBM

Battey et al. 2021 - variational autoencoders (VAE)

Meisner & Albrechtsen (preprint) VAE

Ausmes & Nettelblad 2022 convolutional autoencoders

GCAE
PCA

Yelmen et al. 2021
restricted Boltzman machine
RBM
Generative models (unsupervised learning)

Data with no label

Goal Generate samples having the same distribution as the data

Training data $\sim p_{\text{data}}(x)$
(distribution unknown)

Generated samples $\sim p_{\text{model}}(x)$
Neural networks for unsupervised tasks

(ii) generating realistic genomes that do not belong to a real individual

Probabilistic model of the joint distribution of \( v \) and \( h \)

\[
P(v, h) = \frac{e^{-E(v, h)}}{Z}
\]

\( Z \): partition function

\[
E(v, h) = \sum_{ij} W_{ij} v_i h_j + \text{bias terms}
\]

Restricted Boltzmann Machine (RBM)
Yelmen et al. 2021

Generative Adversarial Networks (GAN)
Yelmen et al. 2021
Unsupervised learning for generating realistic genomes

- Generative models (can also be used for dimension reduction and exploring latent space) Yelmen et al 2021 (GAN and RBM neural networks); Battey et al 2021 (VAE); Ausmees et al 2021
Quality checks

- PCA, tSNE, UMAP
- Allele frequencies (1-point correlation)
- Linkage disequilibrium patterns (2-point correlation)
- Haplotype structure (and 3-point correlation)
- Local ancestry block patterns
- Pairwise distance distributions, ...

→ Are characteristics preserved in generated genomic sequences?
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Task of the tutorial

**Population size history**

**Genetic dataset** $D$

$\approx 6.2 \times 10^5$ base pairs

**Inferred demographic model parameters** $\theta$
**DNADNA:** *Deep neural architectures for DNA,* a toolbox for population genetics inference

Théophile Sanchez*, EM Bray*, Pierre Jobic, Jérémy Guez, Guillaume Charpiat, Jean Cury*, Flora Jay*

---

**Aim:**

- **Reproductibility + sharing** more easily networks within/outside your lab
- **Designing** networks or **training** an already designed network on your training set/task
- **Predicting** evolutionary history for your data using a **pretrained** network

**Beta version → feedback welcome!**

https://hal.archives-ouvertes.fr/hal-03352910v1
**B**

Standard workflow: train a newly implemented network on existing simulations

1/ `dnadna preprocess Demo_preprocessing_config.yml --dataset-config=Demo_dataset_config.yml`
   - describes a previously simulated training set

2/ `dnadna train Demo_training_config.yml --plugin local_net.py`
   - output data and results in different self-contained folder named run.xxx
   - Try new architecture
   - Update hyperparameters

3/ `dnadna predict run.xxx/Demo_run.xxx_best_net.pth Testset/*/npz`
   - plugins are embedded in the .pth file to facilitate sharing and reusing

**C**

Standard workflow: reuse a trained network on one's dataset

1/ `dnadna predict trained_net.pth myData/npz --preprocessing`
   - Contains optimized weight, and all config parameters used for training.
   - Contains means and std to unstandardize prediction
   - Apply same preprocessing e.g. filter out sequences with less than X SNPs and N individuals

**D**

Example of a training config file

```python
# the simulation configuration
simulation:
  label: model_simulation_config.yml
learned_params:
  event_time:
    type: regression
    log_transform: true
    iconv_func: MSE
  event_risk:
    type: regression
    log_transform: true
    iconv_func: MSE
network:
  name: myNet
  params:
    param1: 3
  epochs: 5
  optimizer:
    name: Adam
    params:
      learning_rate: 0.001
      weight_decay: 0.1
```

**E**

Example of a network plugin

```python
from dnadna import nets
from torch.nn.functional import relu

class myNet(nets.Network):
    def __init__(self, param):
        super().__init__(param)
        self.param = param
    def forward(x):
        ...
```

Only change compared to using only pytorch